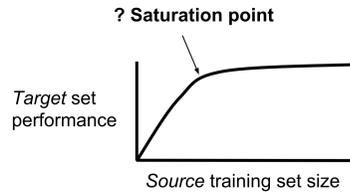


An analysis of transferability of object parts

Main question: What is the minimal amount of supervision needed to perform transfer of object parts?

Overview

- Recent deep learning successes due to large amounts of data
- Question: **When is supervision enough?**
- An analysis of **part detector performance** on a target set w.r.t. source training set size
 - Presence of source/target sets → a domain adaptation problem



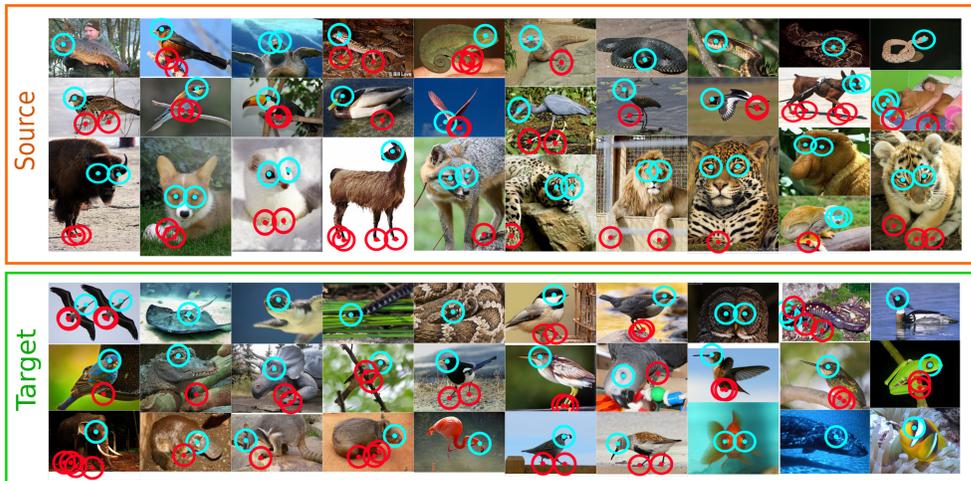
Analysis on animal parts

Parts are shareable among object categories:

- Train a part detector on **source categories**, test on held-out **target categories**
 - Find the saturation point of the detector performance on held-out classes
- Additional analysis: Evaluation of part transfer between categories

A novel Animal Parts dataset for studying transfer learning problems:

- Animal “eye” and “foot” keypoint annotations
- Annotated ~15K ImageNet images of “vertebrate” animals



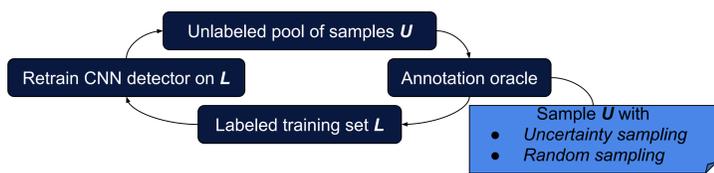
Related problems

- Active Learning [1]** Studies how many images should be annotated s.t. performance saturates ASAP
- Domain adaptation [2]** Animal classes ~ domains; detecting parts ~ the shared task
 - use the domain knowledge to improve the part detector

Proposed methods

All proposed methods utilize the CNN keypoint detector from [3]

Active learning with uncertainty/random sampling [4]

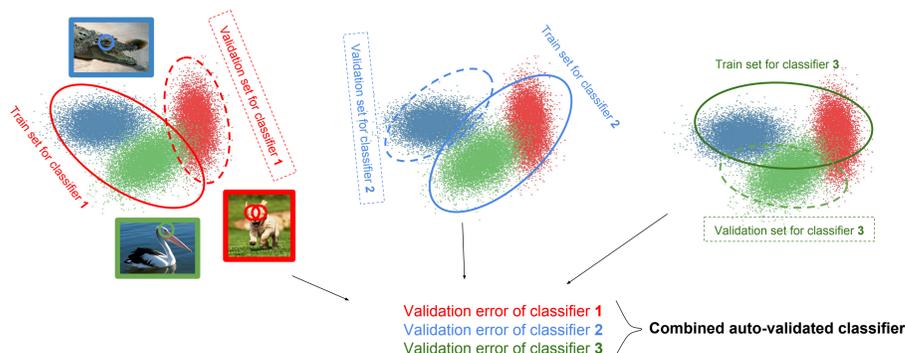


- Originally designed for simple classification problems
- Our problem is in fact an instance of Multiple Instance Active Learning
- We adapt uncertainty sampling for training CNNs in our scenario:
 - The image with the most uncertain pixel-level prediction is selected for annotation
- The first use of an actively trained CNN for image data

Active-transfer learning by auto-validation

During SGD iterations of CNN training perform simultaneously:

Train domain specific classifiers C & Online validation error estimation on C 's complementary domains



- The combined classifier obtained with [5]
- The ensemble classifiers tend to disagree
 - **active sampling by picking samples on which the ensemble disagrees the most** (aka query-by-committee - QBC)

Experiments

Part transferability

Relative difficulty of part detection and part transfer

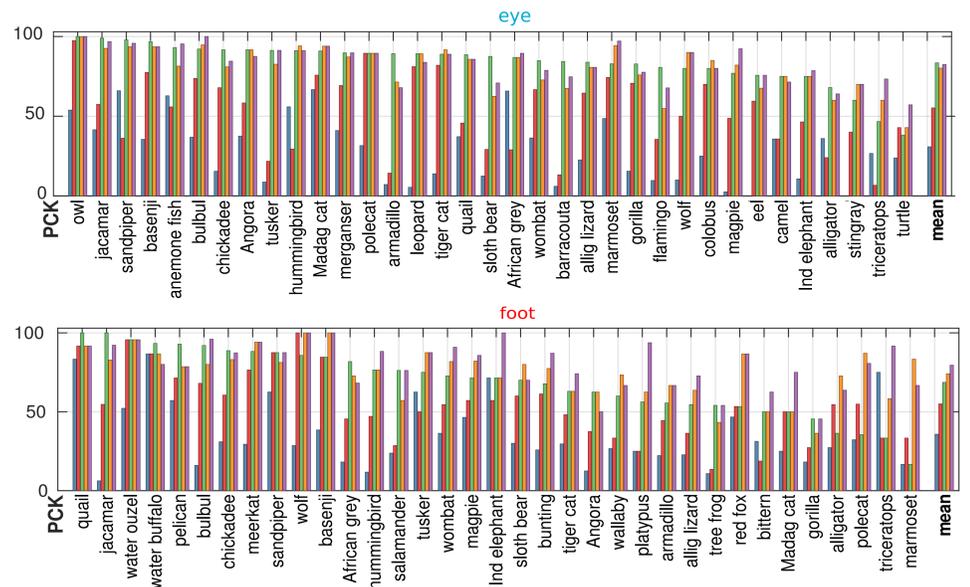
1. Given a target class T , train a CNN part detector on:

- T - the same class
- the T 's nearest class (in semantic distance)
- the T 's farthest class
- the source classes
- all source and target classes



2. The part transfer performance is evaluated by reporting PCK on T :

(PCK - percentage of correctly localized parts)



- Training on source classes (orange) comparable to all source and target classes (purple)
- Training on a diverse set of classes brings satisfactory transfer performance
- Performance degrades significantly when training on the farthest class (blue)
- Demonstrates the relevance of the semantic distance for cross-domain transfer

Active-transfer learning

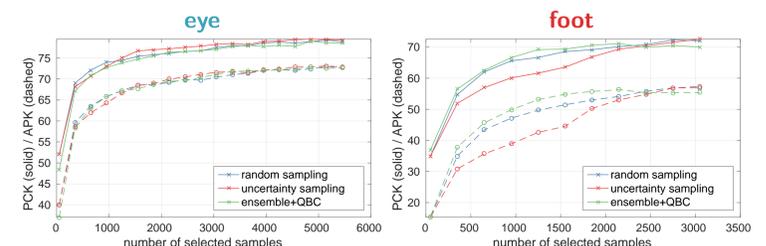
Part detection performance as the number of annotations increases

- Split the set of “vertebrate” classes to 50 source classes and 50 target classes
- Gradually add source class part annotations and report detection performance on the target classes

Comparison of 3 active-transfer learning approaches:

(the text in brackets denotes the label in the figure)

- Random sampling (“random sampling”)
- Active learning by auto-validation (“ensemble+QBC”)
- Uncertainty sampling (“uncertainty sampling”)



- Performance reaches 98% of the accuracy of the fully annotated scenario by providing only a few thousand examples.
- Excellent performance achieved with a handful of samples.
- Ensemble+QBC outperforms other methods on the “foot” keypoints, all methods on par for the “eye” keypoints

Conclusions

- Extensive testing of part transferability
 - Evaluation of part detectors in presence of a domain shift with bounded number of annotations
- Introduced a novel Animal Parts dataset
- Excellent performance achieved only from a limited number of training samples
- The proposed Ensemble+QBC active-transfer learning method outperforms other competitors on the “foot” detection task

References

- D. Cohn, L. Atlas, and R. Ladner, “Improving generalization with active learning,” *Machine learning*, 1994.
- K. Saenko, B. Kulis, M. Fritz, and T. Darrell, “Adapting visual category models to new domains,” in *Proc. ECCV*, 2010.
- S. Tulsiani and J. Malik, “Viewpoints and keypoints,” in *Proc. CVPR*, IEEE, 2015.
- S. Tong and D. Koller, “Support vector machine active learning with applications to text classification,” *JMLR*, 2002.
- A. Krogh and J. Vedelsby, “Neural network ensembles, cross validation, and active learning,” in *Proc. NIPS*, 1995.